

Application of algebraic topology to compatible spatial discretizations

*Five-Laboratory Conference on Computational Mathematics,
Vienna, Austria, 19-23 June 2005*

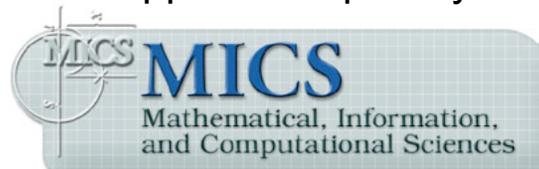
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Motivation

Consistency and approximation are insufficient to avoid unphysical modes

Hyperbolic PDEs (conservation laws)

Failure to maintain conservation lead to **wrong shock locations and speeds.**

MHD

Failure to maintain div-free leads to significant errors for small velocity due to unphysical component in the Lorenz force *Brackbill, Barnes; JCP 35, 1980*

$$\mathbf{F} = \nabla \cdot \underbrace{\left(-\frac{1}{2}(\mathbf{B} \cdot \mathbf{B})\mathbf{I} + \mathbf{B}\mathbf{B} \right)}_{\text{Maxwell stress tensor}} \quad \nabla \cdot \mathbf{B} \neq 0 \Rightarrow \mathbf{F} \cdot \mathbf{B} = (\mathbf{B} \cdot \mathbf{B})\nabla \cdot \mathbf{B} \neq 0 \quad \text{force parallel to } \mathbf{B}$$

Electromagnetics

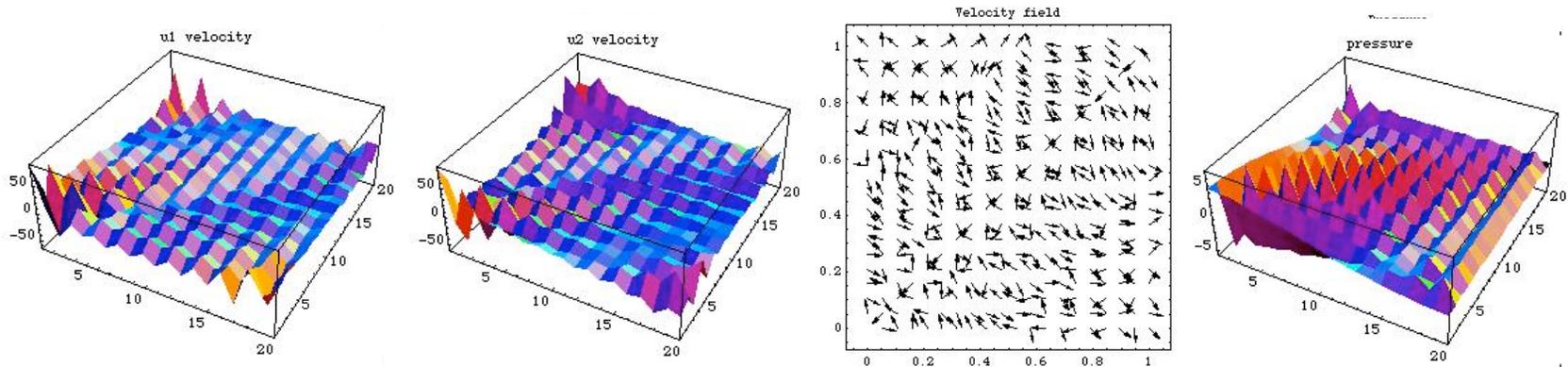
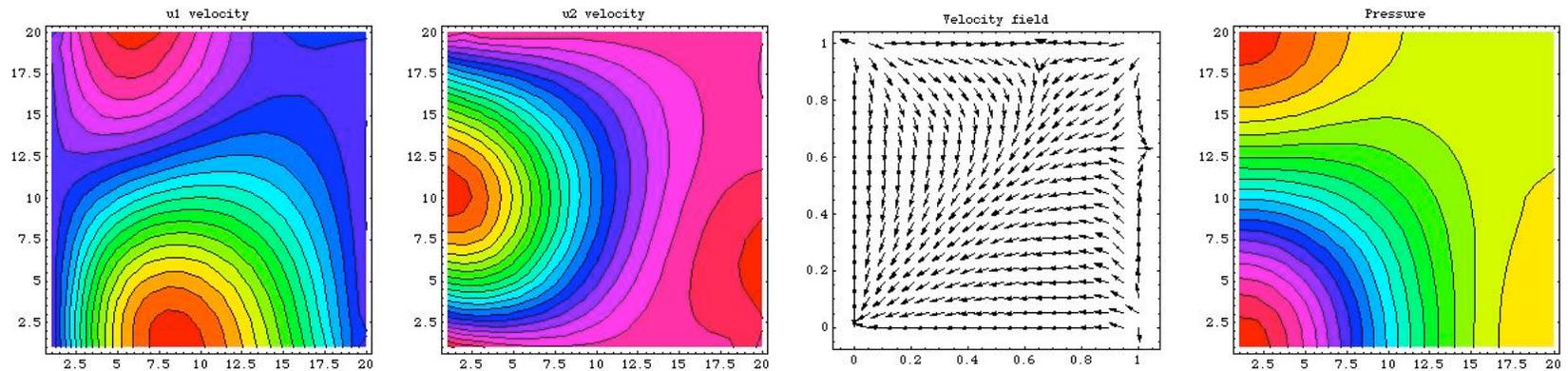
Failure to approximate $\ker(\text{curl})$ by exact gradients gives rise to **spurious modes** and instabilities in transient simulations.

Incompressible flows

Failure to maintain discrete pressure in the **range of the divergence** of the **discrete velocity** leads to spurious modes and/or locking.



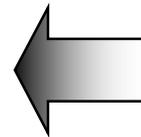
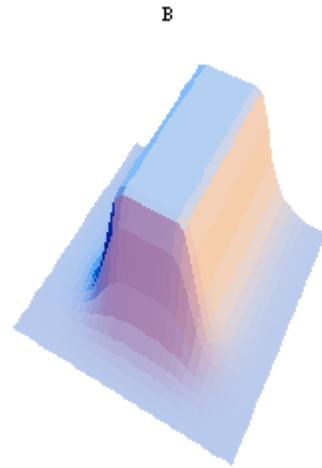
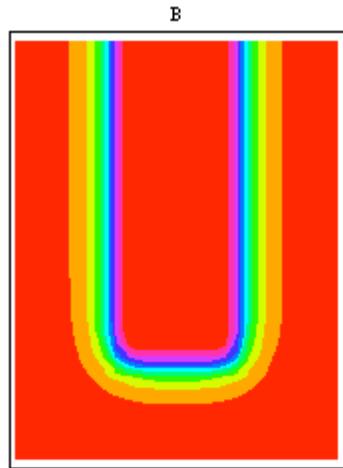
Examples



Collocated Mixed FEM for incompressible flow (same stencil for div and grad) and $P^h \notin \text{div}V^h$

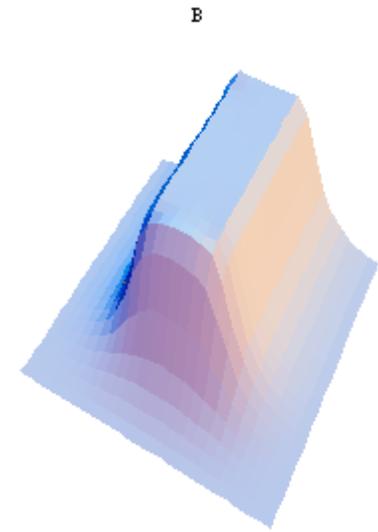
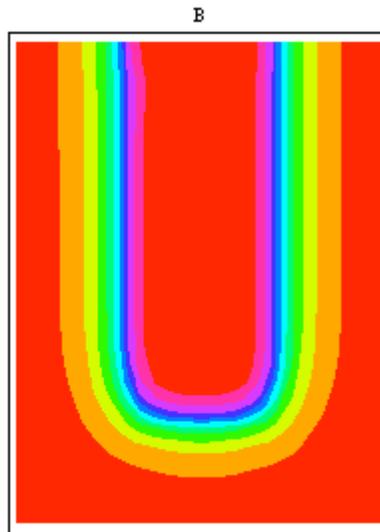
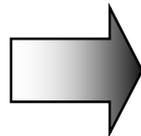


Examples



Low order edge FE solution
 $\text{Ker}(\text{curl}) = \{\text{grad } p\}$

Lagrange C^0 FE solution
 $\text{Ker}(\text{curl}) = \{0\}$





Solutions that work

Lax-Wendroff theorem:

If approximation computed by a **conservative** and **consistent** method converges, then the limit is a **weak solution** of the conservation law.

Grid decomposition property (Fix, Gunzburger, Nicolaidis, 1978)

A **discrete Hodge decomposition** property is **necessary** and **sufficient** for stable and accurate mixed FE discretization of the Kelvin principle.

Staggered FD and FV (MAC, Yee's FDTD, Box integration)

Conservation requires placing **different variables** at **different grid locations** so as to achieve **discrete Stokes** theorem.

Discrete models must reflect mathematical structure of continuum models



How to achieve compatibility?

Compatible discretization requires:

- Mathematical tools to **discover** and **encode** structure of PDEs
- A discrete framework that **mimics** that structure: mutually consistent notions of
 - Discrete vector calculus, Hodge theory, entropy condition, conservation...

In most physical models

- **Fields** are observed **indirectly** by measuring **global** quantities (flux, circulation, etc)
- **Physical laws** are **relationships** between **global** quantities (conservation, equilibrium)

Differential forms provide the tools to **encode** such relationships

- **Integration:** an abstraction of the *measurement* process
- **Differentiation:** gives rise to *local invariants*
- **Poincare Lemma:** expresses *local geometric* relations
- **Stokes Theorem:** gives rise to *global relations*



Algebraic topology approach

Algebraic topology provides the tools to **mimic** the structure

- **Computational grid** is algebraic topological complex
- **k-forms** are encoded as k -cell quantities (k -cochains)
- **Derivative** is provided by the coboundary
- **Inner product** induces combinatorial Hodge theory
- **Singular cohomology** preserved by the complex

Framework for mimetic discretizations

- **Translation:** Fields \rightarrow forms \rightarrow cochains
- **Basic mappings:** **reduction** and **reconstruction**
 - **Combinatorial operations:** induced by **reduction** map
 - **Natural operations:** induced by **reconstruction** map
 - **Derived operations:** induced by **natural** operations

*Branin (1966), Dodzuik (1976), Hyman & Scovel (1988-92), Nicolaidis (1993),
Dezin (1995), Shashkov (1990-), Mattiussi (1997), Schwalm (1999), Teixeira
(2001)*

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Differential Forms

Smooth differential forms	$\Lambda^k(\Omega): x \rightarrow \omega(x) \in \Lambda^k(T_x\Omega)$
DeRham complex	$\mathbf{R} \rightarrow \Lambda^0 \xrightarrow{d} \Lambda^1 \xrightarrow{d} \Lambda^2 \xrightarrow{d} \Lambda^3 \rightarrow 0$
Metric conjugation	$*: \Lambda^k(T_x\Omega) \rightarrow \Lambda^{n-k}(T_x\Omega) \Leftrightarrow \omega \wedge *\xi = (\omega, \xi)_x \omega_n$
L² inner product on $\Lambda^k(\Omega)$	$(\omega, \xi)_\Omega = \int_\Omega (\omega, \xi)_x \omega_n \Rightarrow (\omega, \xi)_\Omega = \int_\Omega \omega \wedge *\xi$
Codifferential	$d^*: \Lambda^{k+1}(\Omega) \rightarrow \Lambda^k(\Omega) \Leftrightarrow (d\omega, \xi)_\Omega = (\omega, d^*\xi)_\Omega$
Hodge Laplacian	$\Delta: \Lambda^k(\Omega) \rightarrow \Lambda^k(\Omega) \rightarrow \Delta = dd^* + d^*d$
Completion of $\Lambda^k(\Omega)$	$\Lambda^k(L^2, \Omega)$
Sobolev spaces	$\Lambda^k(d, \Omega) = \{ \omega \in \Lambda^k(L^2, \Omega) \mid d\omega \in \Lambda^{k+1}(L^2, \Omega) \}$

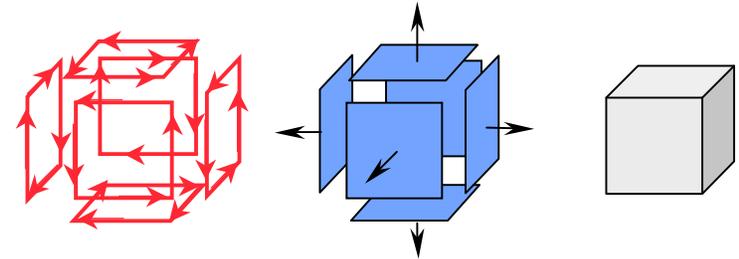


Chains and cochains

Computational grid = Chain complex

$$\partial : C_k \rightarrow C_{k-1}$$

$$\partial\partial = 0 \quad C_0 \xleftarrow{\partial} C_1 \xleftarrow{\partial} C_2 \xleftarrow{\partial} C_3$$



$$0 = \partial\partial K^3 \xleftarrow{\partial} \partial K^3 \xleftarrow{\partial} K^3$$

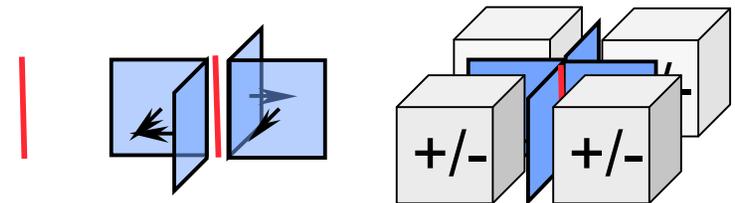
Field representation = Cochain complex

$$C^k = L(C_k, \mathbf{R}) = C_k^* \quad \langle \sigma^i, \sigma_j \rangle = \delta_{ij}$$

$$K^1 \xrightarrow{\delta} \delta K^1 \xrightarrow{\delta} \delta\delta K^1 = 0$$

$$\delta : C^k \rightarrow C^{k+1} \quad \langle \omega, \partial\eta \rangle = \langle \delta\omega, \eta \rangle$$

$$\delta\delta = 0 \quad C^0 \xrightarrow{\delta} C^1 \xrightarrow{\delta} C^2 \xrightarrow{\delta} C^3$$





Basic mappings

Reduction

$$\mathcal{R} : \Lambda^k(L^2, \Omega) \rightarrow C^k$$

Natural choice

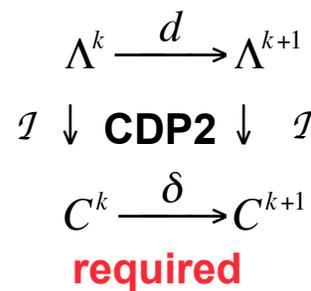
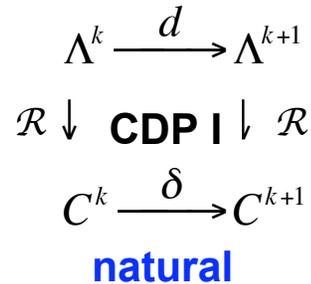
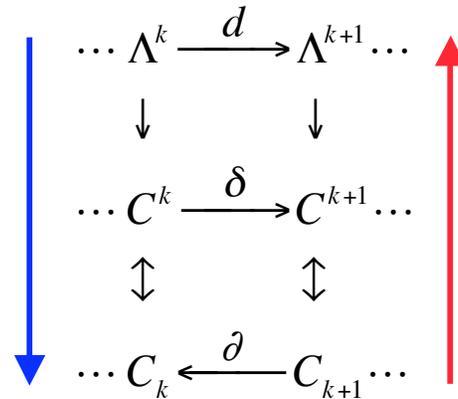
$$\langle \mathcal{R}\omega, \sigma \rangle = \int_{\sigma} \omega$$

DeRham map

$$\mathcal{R}d = \delta\mathcal{R}$$

Proof

$$\begin{aligned} \langle \delta\mathcal{R}\omega, c \rangle &= \langle \mathcal{R}\omega, \partial c \rangle = \\ \int_{\partial c} \omega &= \int_c d\omega = \langle \mathcal{R}d\omega, c \rangle \end{aligned}$$



$$\text{Range } \mathcal{I}\mathcal{R} = \Lambda^k(L^2, K) \subset \Lambda^k(L^2, \Omega)$$

$$\text{Range } \mathcal{I}\mathcal{R} = \Lambda^k(d, K) \subset \Lambda^k(d, \Omega)$$

Reconstruction

$$\mathcal{I} : C^k \rightarrow \Lambda^k(L^2, \Omega)$$

No natural choice

$$\mathcal{R}\mathcal{I} = id$$

$$\mathcal{I}\mathcal{R} = id + O(h^s)$$

$$\ker \mathcal{I} = 0$$

Conforming

$$\mathcal{I} : C^k \rightarrow \Lambda^k(d, \Omega)$$

$$\mathcal{I}d = \delta\mathcal{I}$$



Combinatorial operations

Discrete derivative

Forms are dual to **manifolds**

$$\langle d\omega, \Omega \rangle = \langle \omega, \partial\Omega \rangle$$

Cochains are dual to **chains**

$$\langle \delta a, \sigma \rangle = \langle a, \partial\sigma \rangle$$

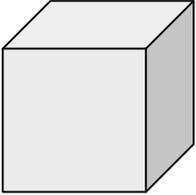
δ approximates d
on cochains

Discrete integral

$$\int_{\sigma} a = \langle a, \sigma \rangle$$

Stokes theorem

$$\langle \delta a, \sigma \rangle = \langle a, \partial\sigma \rangle$$

grad	curl	div
$\begin{pmatrix} -1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 1 & 0 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \\ 0 & 0 & -1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & 0 & -1 & 0 & 1 & 0 \end{pmatrix}$	$\begin{pmatrix} 1 & 1 & -1 & -1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & -1 & -1 \\ 1 & 0 & 0 & 0 & -1 & 1 & 0 & 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 & -1 & 0 & 0 & 1 & 0 & 0 & 0 & -1 \\ 0 & 1 & 0 & 0 & 0 & -1 & 1 & 0 & 0 & -1 & 0 & 0 \end{pmatrix}$	$(-1 \ 1 \ 1 \ -1 \ -1 \ 1)$
	$\delta\delta = 0$ $\mathcal{R}d = \delta\mathcal{R}$	



Natural and derived operations

Natural	Inner product	$(a,b)_x = (\mathcal{I}a, \mathcal{I}b)_x$	$(a,b)_\Omega = \int_\Omega (a,b)_x \omega_n = (\mathcal{I}a, \mathcal{I}b)_\Omega$
	Wedge product	$\wedge : C^k \times C^l \mapsto C^{k+l}$	$a \wedge b = \mathcal{R}(\mathcal{I}a \wedge \mathcal{I}b)$
Derived	Adjoint derivative	$\delta^* : C^{k+1} \mapsto C^k$	$(\delta^* a, b)_\Omega = (a, \delta b)_\Omega$
	Provides a second set of grad , div and curl operators. Scalars encoded as 0 or 3-forms, vectors as 1 or 2-forms, derivative choice depends on encoding.		
	Discrete Laplacian	$D : C^k \mapsto C^k$	$D = \delta^* \delta + \delta \delta^*$

Derived operations are necessary to avoid **internal inconsistencies** between the discrete operations: \mathcal{I} is only **approximate inverse** of \mathcal{R} and natural operations will clash

Example **Natural adjoint** $d^* = (-1)^k * d^* \longrightarrow \delta^* = (-1)^k \mathcal{R} * d^* \mathcal{I}$

\mathcal{I} must be regular and $(\delta^* a, b)_\Omega = (a, \delta b)_\Omega + O(h^s) \Rightarrow \delta^*$ not true adjoint



Mimetic properties

Discrete Poincare lemma (existence of potentials in contractible domains)

$$d\omega_k = 0 \Rightarrow \omega_k = d\omega_{k+1}$$

$$\delta c^k = 0 \Rightarrow c^k = \delta c^{k+1}$$

Discrete Stokes Theorem

$$\langle d\omega_{k-1}, c_k \rangle = \langle \omega_{k-1}, \partial c_k \rangle$$

$$\langle \delta c^{k-1}, c_k \rangle = \langle c^{k-1}, \partial c_k \rangle$$

Discrete “Vector Calculus”

$$dd = 0$$

$$\delta\delta = \delta^* \delta^* = 0$$

$$\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$$

$$a \wedge b = (-1)^{kl} b \wedge a$$

$$d(\omega \wedge \eta) = d\omega \wedge \eta + (-1)^k \omega \wedge d\eta$$

$$\delta(a \wedge b) = \delta a \wedge b + (-1)^k a \wedge \delta b \quad (\text{Regular } \mathcal{I})$$

Any feature of the continuum system that is implied by differential forms calculus is inherited by the discrete model

Called **mimetic** property by Hyman and Scovel (1988)



Mimetic properties

Inner product induces combinatorial Hodge theory on cochains

$$\begin{array}{ccc} \text{Co-cycles of } (W_0, W_1, W_2, W_3) & \xrightarrow{\mathcal{R}} & \text{co-cycles of } (C^0, C^1, C^2, C^3) \\ d\omega = 0 & \Rightarrow & \delta\mathcal{R}\omega = 0 \end{array}$$

Discrete Harmonic forms

$$H^k(\Omega) = \{\eta \in \Lambda^k(\Omega) \mid d\eta = d^*\eta = 0\} \qquad H^k(K) = \{c^k \in C^k \mid \delta c^k = \delta^* c^k = 0\}$$

Discrete Hodge decomposition

$$\omega = d\rho + \eta + d^*\sigma \qquad a = \delta b + h + \delta^*c$$

Theorem

$$\dim\ker(\Delta) = \dim\ker(D)$$

Remarkable property of the mimetic D - kernel size is a **topological invariant!**



Discrete * operation

Natural definition

$$*_N: C^k \mapsto C^{n-k} \qquad *_N = \mathcal{R} * \mathcal{I}$$

Derived definition

$$*_D: C^k \mapsto C^{n-k} \qquad \int_{\Omega} a \wedge *_D b = (a, b)_{\Omega} \quad \text{mimics} \quad (\omega, \xi)_{\Omega} = \int_{\Omega} \omega \wedge * \xi$$

Theorem

$$*_N \mathcal{R} \omega^h = \mathcal{R} * \omega^h \quad \forall \omega^h \in \text{Range}(\mathcal{I}\mathcal{R}) \qquad \text{CDP on the range}$$

$$\int_{\Omega} \mathcal{I}\mathcal{R}(\mathcal{I}a \wedge \mathcal{I} *_D b) = \int_{\Omega} (\mathcal{I}a \wedge * \mathcal{I}b) \qquad \text{Weak CDP}$$

$$\int_{\Omega} b \wedge *_N b = (a, b)_{\Omega} + O(h^s) \qquad *_N = *_D + O(h^s)$$



Problems with the discrete *

Action of * must be coordinated with two other discrete operations

	(\cdot, \cdot)	\wedge	δ^*	\mathcal{R}	\mathcal{I}
$*_N$	—	—	—	✓	—
$*_D$	✓	✓	—	—	—

Analytic * is a **local, invertible** operation \Rightarrow **positive diagonal** matrix

$$\dim C^k \neq \dim C^{n-k} \Rightarrow *_N: C^k \mapsto C^{n-k} \text{ cannot be a square matrix!}$$

Construction of * is nontrivial task unless primal-dual grid is used!



Implications

A consistent discrete framework requires a choice of a primary operation
either $*$ or (\cdot, \cdot) but not both

A **discrete $*$** is the primary concept in Hiptmair (2000), Bossavit (1999)

- Inner product derived from discrete $*$
- Used in explicit discretization of material laws

The **natural inner product** is the primary operation in our approach

- **Sufficient** to give rise to combinatorial Hodge theory on cochains
- **Easier** to define than a discrete $*$ operation
- **Incorporate** material laws in the natural inner product, or
- **Enforce** material laws **weakly** (justified by their approximate nature)

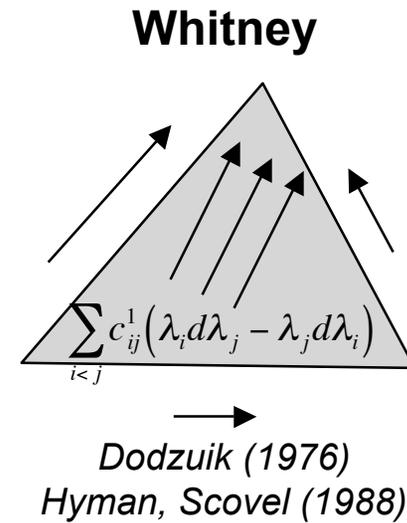
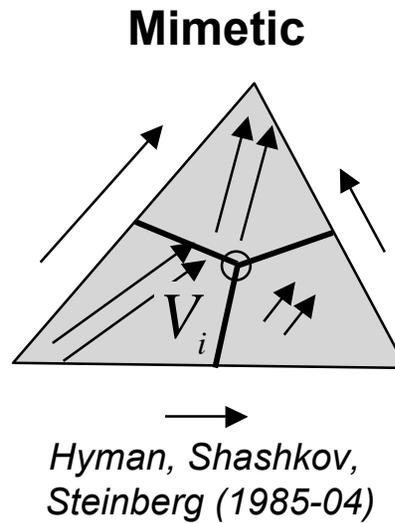
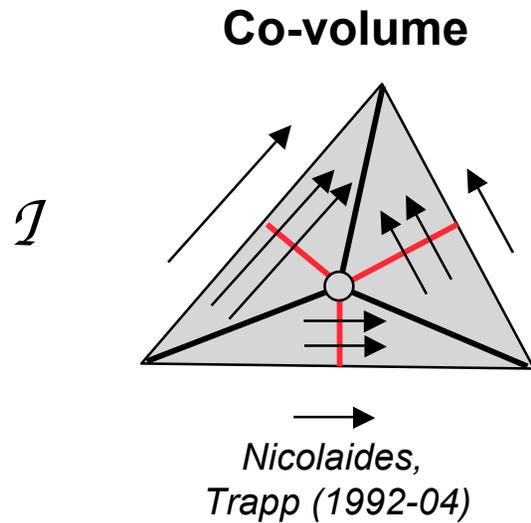


Algebraic equivalents

Operation	Matrix form	type
δ	\mathbf{D}_k	$\{-1,0,1\}$
(\cdot, \cdot)	\mathbf{M}_k	SPD
$a_1 \wedge b_1$	$\sum \mathbf{W}_{11}$	Skew symm. $\mathbf{W}_{12}^T = \mathbf{W}_{21}$
$a_1 \wedge b_2$	$\sum \mathbf{W}_{12}$	
$b_2 \wedge a_1$	$\sum \mathbf{W}_{21}$	
δ^*	$\mathbf{M}_k^{-1} \mathbf{D}_k^T \mathbf{M}_{k+1}$	rectangular
\mathcal{D}	$\mathbf{M}_k^{-1} \mathbf{D}_k^T \mathbf{M}_{k+1} \mathbf{D}_k + \mathbf{D}_{k-1} \mathbf{M}_{k-1}^{-1} \mathbf{D}_{k-1}^T \mathbf{M}_k$	square
$*_D$	$\mathbf{W}_{12}(*_D \mathbf{a}) = \mathbf{M}_3 \mathbf{a}$	pair



Reconstruction and natural inner products



\mathbf{M}

$$\begin{pmatrix} h_1 h_1^\perp & & \\ & h_2 h_2^\perp & \\ & & h_3 h_3^\perp \end{pmatrix}$$

$$\begin{pmatrix} \frac{V_2}{\sin^2 \phi_2} + \frac{V_3}{\sin^2 \phi_3} & \frac{V_3 \cos \phi_3}{\sin^2 \phi_3} & \frac{V_2 \cos \phi_2}{\sin^2 \phi_2} \\ \frac{V_3 \cos \phi_3}{\sin^2 \phi_3} & \frac{V_1}{\sin^2 \phi_1} + \frac{V_3}{\sin^2 \phi_3} & \frac{V_1 \cos \phi_1}{\sin^2 \phi_1} \\ \frac{V_2 \cos \phi_2}{\sin^2 \phi_2} & \frac{V_1 \cos \phi_1}{\sin^2 \phi_1} & \frac{V_1}{\sin^2 \phi_1} + \frac{V_2}{\sin^2 \phi_2} \end{pmatrix}$$

$$\omega_{ij}^1 = \lambda_i d\lambda_j - \lambda_j d\lambda_i$$

$$\begin{pmatrix} \dots & \dots & \dots \\ \dots & (w_{ij}, w_{kl}) & \dots \\ \dots & \dots & \dots \end{pmatrix}$$

δ^* **local**

non-local

non-local



Mimetic discretization: translation to forms

1st order PDE with material laws

$$\begin{aligned} \nabla \times \mathbf{E} &= -\frac{\partial \mathbf{B}}{\partial t} & \mathbf{J} &= \sigma \mathbf{E} \\ \nabla \times \mathbf{H} &= \mathbf{J} & \mathbf{B} &= \mu \mathbf{H} \end{aligned}$$



$$\begin{aligned} de &= -d_t b & *_{\sigma^{-1}} j &= e \\ dh &= j & *_{\mu^{-1}} b &= h \end{aligned}$$

1st order PDE with codifferentials

$$\begin{aligned} \nabla \times \mathbf{E} &= -\frac{\partial \mathbf{B}}{\partial t} \\ \frac{1}{\sigma} \nabla \times \frac{1}{\mu} \mathbf{B} &= \mathbf{E} \end{aligned}$$



$$\begin{aligned} de &= -d_t b \\ e &= *_{\sigma^{-1}} d *_{\mu^{-1}} b \end{aligned}$$

2nd order PDE

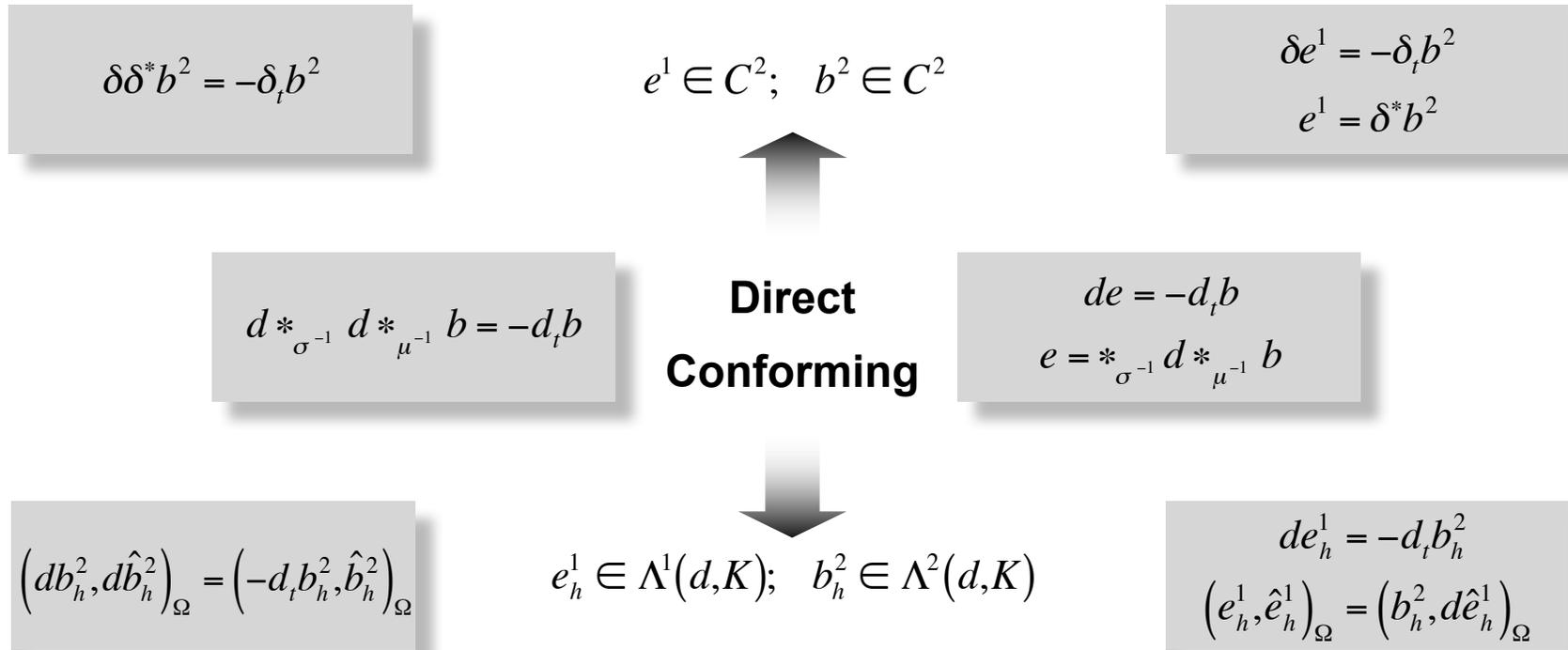
$$\nabla \times \frac{1}{\sigma} \nabla \times \frac{1}{\mu} \mathbf{B} = -\frac{\partial \mathbf{B}}{\partial t}$$



$$d *_{\sigma^{-1}} d *_{\mu^{-1}} b = -d_t b$$



Direct and conforming mimetic models



Theorem (Bochev & Hyman)

Assume that \mathcal{I} is **regular** reconstruction operator. Then, the **direct** and the **conforming** mimetic methods are completely equivalent.



Mimetic models with weak material laws

Translate to an equivalent constrained optimization problem

$$\begin{aligned}
 de &= -d_t b & *_{\sigma^{-1}} j &= e \\
 dh &= j & *_{\mu^{-1}} b &= h
 \end{aligned}$$



$$\begin{aligned}
 &\min \frac{1}{2} \left(\|j - *_{\sigma} e\|^2 + \|b - *_{\mu} h\|^2 \right) \\
 &\text{subject to } de = -d_t b \text{ and } dh = j
 \end{aligned}$$

Conforming

$$\begin{aligned}
 &\min \frac{1}{2} \left(\|j_h^2 - e_h^1\|^2 + \|b_h^2 - h_h^1\|^2 \right) \\
 &\text{subject to } de_h^1 = -d_t b_h^2 \text{ and } dh_h^1 = j_h^2
 \end{aligned}$$

Mimetic discretization

$$\begin{aligned}
 &\min \frac{1}{2} \left(\|j^2 - e^1\|^2 + \|b^2 - h^1\|^2 \right) \\
 &\text{subject to } \delta e^1 = -\delta_t b^2 \text{ and } \delta h^1 = j^2
 \end{aligned}$$

Direct

Advantages

- Does not require a primal-dual grid complex
- Explicit discretization of material laws is avoided
- Construction of a discrete * operation not required



Conclusions

- ❑ **Algebraic topology** provides powerful tools for mimetic discretizations
- ❑ We presented a **mimetic framework** where:
 - All operations defined by **two mappings**: reduction \mathcal{R} and reconstruction \mathcal{I}
 - The central concept is the natural inner product
- ❑ The framework consists of three operation types
 - **Combinatorial** integral and derivative
 - **Natural** inner product and wedge product
 - **Derived** adjoint derivative, Hodge Laplacian
- ❑ Choice of **natural** and **derived** operations governed by **internal consistency**
- ❑ Operations provide **discrete vector calculus** and **combinatorial Hodge theory**
- ❑ Instead of explicit discretization of material laws they are
 - **incorporated** in the inner product or
 - **imposed weakly** through equivalent constrained optimization problem
- ❑ **Direct** and **conforming** mimetic methods are **identical** for regular \mathcal{I}
 - Differences between FV, FD and FE are largely **superficial**
 - Distinctions arise primarily from the **choice** of reconstruction operators